

## Lampiran

```
#include <LiquidCrystal_I2C.h>

#include <virtuabotixRTC.h>

LiquidCrystal_I2C lcd(0x3f,2,1,0,4,5,6,7,3,POSITIVE);

virtuabotixRTC myRTC(9, 10, 11); //KAKI rtc(clk,dat,rs)

#define relay 12

#define sensor1 A0

#define sensor2 A1

#define sensor3 A2

int pilih,detik,x,menit,m;

void setup() {

    // put your setup code here, to run once:

    Serial.begin(9600);

    myRTC.setDS1302Time(50, 59, 23, 6, 10, 1, 2014); //detik, menit, jam, tanggal,

    bulan, tahun

    pinMode(relay, OUTPUT);

    pinMode(sensor1, INPUT_PULLUP);

    pinMode(sensor2, INPUT_PULLUP);
```

```

pinMode(sensor3, INPUT_PULLUP);

lcd.begin(16, 2);

lcd.setCursor(0,0);

lcd.print(" SKRIPSI 2018 ");

lcd.setCursor(0,1);

lcd.print(" TEKNIK ELEKTRO ");

delay(2000);

lcd.clear();
}

void loop() {
  kerja();
  //rtc();
  //sensor();
}

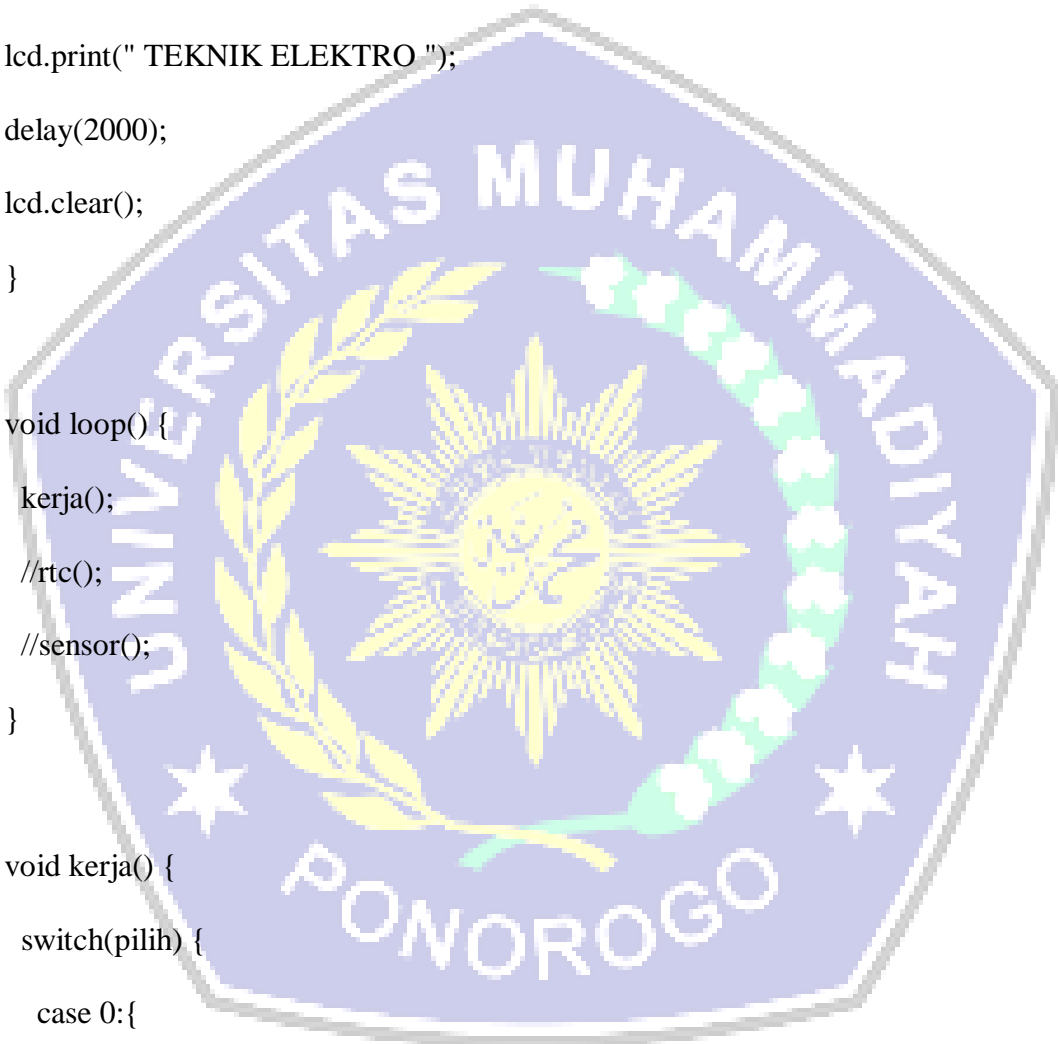
void kerja() {
  switch(pilih) {
    case 0:{
      Serial.println("case 0");

      delay(1000);

      pilih=1;

      break;

```



```

}

case 1:{

  Serial.println("case 1");

  x=0;

  rtc();

  sensor();

  digitalWrite(relay, LOW);

  if(digitalRead(sensor1)==1    &&    digitalWrite(sensor2)==1    &&
digitalRead(sensor3)==1) {

    pilih=2;

    break;

  }

  if(myRTC.hours==0 && myRTC.minutes==0 && myRTC.seconds==30) {

    pilih=3;

    break;

  }

  if(myRTC.hours==0 && myRTC.minutes==1 && myRTC.seconds==0) {

    pilih=3;

    break;

  }

  if(myRTC.hours==0 && myRTC.minutes==1 && myRTC.seconds==30) {

    pilih=3;

    break;

```

```

}

if(myRTC.hours==0 && myRTC.minutes==2 && myRTC.seconds==0) {

    pilih=3;

    break;

}

break;

}

case 2:{

Serial.println("case 2");

digitalWrite(relay, HIGH);

while(x<5) {

rtc();

lcd.setCursor(0,1);

lcd.print("KOTORAN MENUMPUK");

delay(1000);

lcd.clear();

rtc();

lcd.setCursor(1,1);

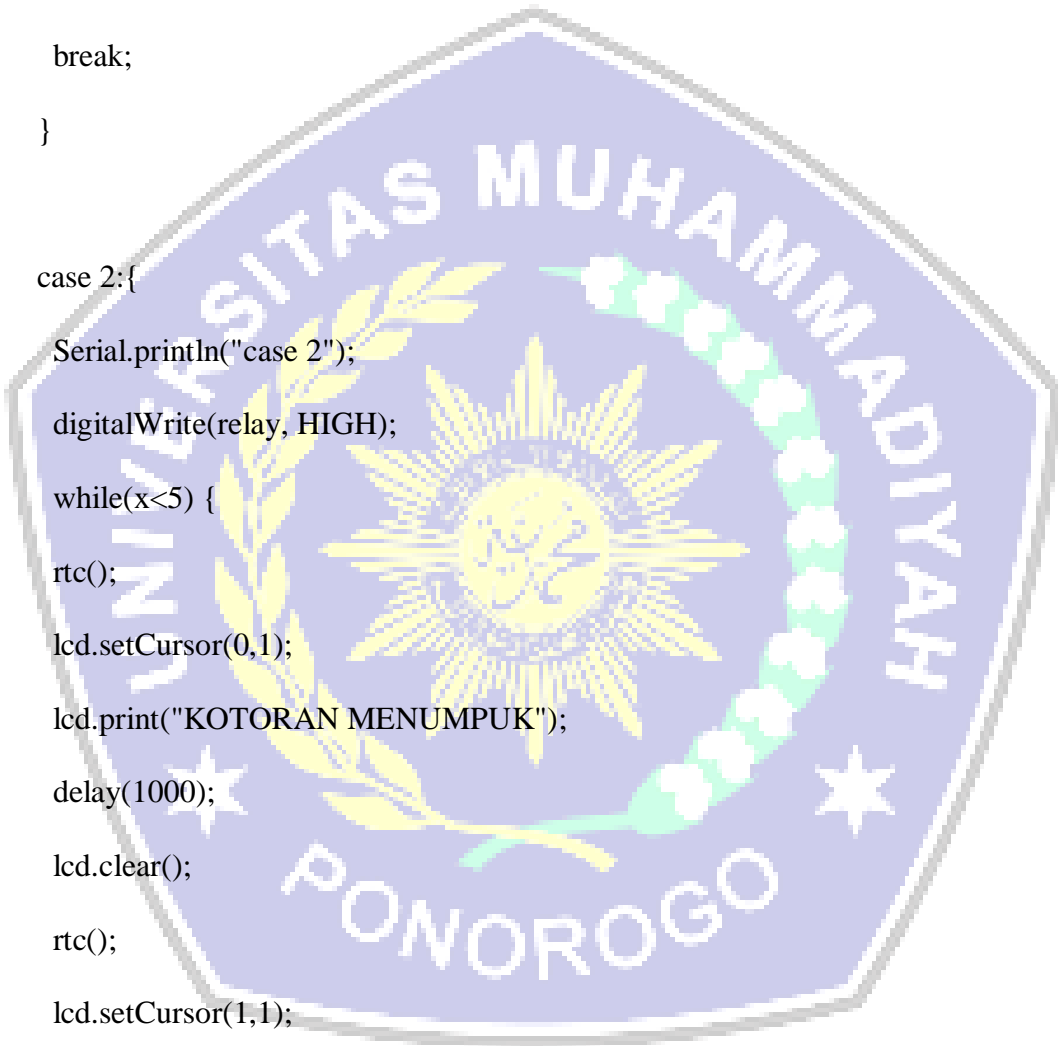
lcd.print(" PEMBERSIHAN ");

delay(1000);

lcd.clear();

x++;

```



```

}

pilih=4;

break;

}

case 3:{

Serial.println("case 3");

while(x<5) {

sensor();

digitalWrite(relay, HIGH);

lcd.setCursor(1,0);

lcd.print(" SAATNYA UNTUK ");

delay(1000);

lcd.clear();

sensor();

lcd.setCursor(1,0);

lcd.print(" PEMBERSIHAN ");

delay(1000);

lcd.clear();

x++;

}

pilih=4;

break;

}

```



```

case 4:{
    digitalWrite(relay, LOW);

    rtc();

    lcd.clear();

    delay(2000);

    pilih=1;

    break;
}
}
}

void sensor() {
    lcd.setCursor(1,1);
    lcd.print("Status >");
    lcd.setCursor(10,1);
    lcd.print(digitalRead(sensor1));

    lcd.setCursor(12,1);
    lcd.print(digitalRead(sensor2));

    lcd.setCursor(14,1);

    lcd.print(digitalRead(sensor3));
}

void rtc() {

```



```
myRTC.updateTime();  
  
lcd.setCursor(4,0);  
  
lcd.print(myRTC.hours);  
  
lcd.setCursor(6,0);  
  
lcd.print(":");  
  
lcd.setCursor(7,0);  
  
lcd.print(myRTC.minutes);  
  
lcd.setCursor(9,0);  
  
lcd.print(":");  
  
lcd.setCursor(10,0);  
  
lcd.print(myRTC.seconds);  
  
if(myRTC.seconds==59) {  
    lcd.clear();  
}  
}
```

