

LAMPIRAN

Lampiran 1

```
#define BLYNK_PRINT
#define BLYNK_TEMPLATE_ID "TMPLgh9HyVCK5"
#define BLYNK_DEVICE_NAME "Alat Kontrol Pengairan Sawah ABCD"
#define BLYNK_AUTH_TOKEN "nKJyA9mQjtzjFKNQdtJMZyHaSFd2tiPs"

#include <ESP8266_Lib.h>
#include <BlynkSimpleShieldEsp8266.h>


// You should get Auth Token in the Blynk App.
char auth[] = BLYNK_AUTH_TOKEN;

// Your WiFi credentials.
// Set password
char ssid[] = "Republik Indonesia";
char pass[] = "88888888";

// Hardware Serial on Mega
//#define EspSerial Serial1

// or Software Serial on Uno
#include "SoftwareSerialMod.h"
SoftwareSerial EspSerial(2, 3);

// Your ESP8266 baud rate:
#define ESP8266_BAUD 9600
```

The logo of Universitas Muhammadiyah Ponorogo is a purple shield-shaped emblem. It features a central sunburst with Arabic calligraphy, surrounded by a green and white floral wreath. The text "UNIVERSITAS MUHAMMADIYAH" is written in white along the top inner edge, and "PONOROGO" is written along the bottom inner edge. A white star is positioned at the bottom right of the shield.

```
ESP8266 wifi(&EspSerial);
```

```
#include <Servo.h>
```

```
// create servo objects
```

```
Servo servo_pintu_A;
```

```
Servo servo_pintu_B;
```

```
Servo servo_pintu_C;
```

```
Servo servo_pintu_D;
```

```
#define relay_pompa_A 8
```

```
#define relay_pompa_B 7
```

```
#define relay_pompa_C 5
```

```
#define relay_pompa_D 4
```

```
#include "PinChangeInterrupt.h"
```

```
// Modify these at your leisure.
```

```
#define pin_flow_meter_A A0
```

```
#define pin_flow_meter_B A1
```

```
#define pin_flow_meter_C A2
```

```
#define pin_flow_meter_D A3
```

```
LYNK_WRITE(V0)
```

```
{
```

```
int state = param.asInt();
```

```
if (state == 0)
```

```
{
```



```

servo_pintu_A.write(74);
Serial.println("Servo A Tertutup");
}
if (state == 1)
{
servo_pintu_A.write(135);
Serial.println("Servo A Terbuka");
}
}
servo_pintu_A.attach(11);
servo_pintu_B.attach(10);
servo_pintu_C.attach(9);
servo_pintu_D.attach(6);

servo_pintu_A.write(74);
servo_pintu_B.write(125);
servo_pintu_C.write(70);
servo_pintu_D.write(131);
delay(2000);
}
}

void setup()
{
pinMode(relay_pompa_A, OUTPUT);
pinMode(relay_pompa_B, OUTPUT);
pinMode(relay_pompa_C, OUTPUT);
pinMode(relay_pompa_D, OUTPUT);
digitalWrite(relay_pompa_A, HIGH);
digitalWrite(relay_pompa_B, HIGH);

```



```
digitalWrite(relay_pompa_C, HIGH);  
digitalWrite(relay_pompa_D, HIGH);  
  
// set pins to input  
pinMode(pin_flow_meter_A, INPUT_PULLUP);  
pinMode(pin_flow_meter_B, INPUT_PULLUP);  
pinMode(pin_flow_meter_C, INPUT_PULLUP);  
pinMode(pin_flow_meter_D, INPUT_PULLUP);
```



Lampiran 2

